



# GUJARAT TECHNOLOGICAL UNIVERSITY

Program Name: Diploma Engineering

Level: Diploma

Branch: Electrical Engineering / Renewable Energy

Subject Code: DI05000211

Subject Name: Digital Signal Controller

w. e. f. Academic Year:	2026-27
Semester:	5 <sup>th</sup>
Category of the Course:	PEC-04

<b>Prerequisite:</b>	<b>Basic concepts of Electrical &amp; Electronics (Analog &amp; Digital) Engineering, Understanding of C Programming language, Basics of Microprocessors and Microcontrollers.</b>
<b>Rationale:</b>	Digital Signal Controllers (DSC) and their role in modern electrical engineering applications. As power electronics, motor drives, and renewable energy systems continue to grow, the need for efficient real-time control has become essential, with 32-bit controllers like STM32 and TI C2000 playing a key role. The course covers hardware architecture, embedded C programming, real-time control techniques, and peripheral interfacing, along with practical applications in converters, inverters, and motor control. It also introduces advanced topics such as PLL and FPGA for high-speed and synchronized systems. Overall, the course bridges the gap between theoretical knowledge and practical implementation, preparing students for careers in power electronics, embedded systems, automation, and renewable energy.

## Course Outcome:

After Completion of the Course, Student will able to:

No	Course Outcomes	RBT Level
01	Differentiate the architecture and features of Digital Signal Controllers (DSC) and 32-bit controllers	U
02	Develop embedded C programs using control structures, interrupts, and peripheral interfacing techniques.	A
03	Apply Digital Signal Controllers in power electronics, motor control, and renewable energy systems and analyze their performance.	A
04	Implement STM32 and TI controller-based systems for PWM generation, ADC interfacing, and real-time control applications.	A
05	Explain advanced concepts such as PLL and FPGA and their applications in high-speed and synchronized systems.	U

\*Revised Bloom's Taxonomy (RBT)



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## Teaching and Examination Scheme:

Teaching Scheme (in Hours)			Total Credits L+T+ (PR/2)	Assessment Pattern and Marks				Total Marks
L	T	PR	C	Theory		Tutorial / Practical		
				ESE (E)	PA(M)	PA(I)	ESE (V)	
3	0	2	4	70	30	30	20	150

## Course Content:

Unit No.	Content	No. of Hours	% of Weightage
1.	<p><b>Fundamentals of Digital Signal Controllers &amp; Hardware Architecture</b> Contents:</p> <ul style="list-style-type: none"> <li>➤ Introduction to Digital Signal Controllers (DSC): Definition and need in electrical engineering, Difference between Microcontroller, Microprocessor and DSC, Applications in power electronics, motor control and renewable energy.</li> <li>➤ Overview of 32-bit Controllers: Need for 32-bit controllers, Introduction to STM32 and TI C2000.</li> <li>➤ Hardware Architecture of DSC: Block diagram of DSC, CPU components (ALU, Control Unit, Registers), Harvard vs Von-Neumann architecture, Clock system and performance.</li> <li>➤ On-Chip Peripherals: GPIO, Timers, ADC, DAC, Communication peripherals (UART, SPI, I2C).</li> <li>➤ Memory System and Registers: Flash, SRAM, EEPROM, Special Function Registers (SFR), Register-level programming.</li> <li>➤ Interrupt Processing: Concept and types (External, Timer, ADC), Interrupt priority and vector table, Basic interrupt flow.</li> </ul>	12	27%
2.	<p><b>Embedded C Programming for 32-bit Controllers</b> Contents:</p> <ul style="list-style-type: none"> <li>➤ Introduction to Embedded C: Difference between C and Embedded C, Structure of embedded program, Header files and libraries.</li> </ul>	10	22 %



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	<ul style="list-style-type: none"> <li>➤ Development Environment (IDE): Introduction to STM32CubeIDE, Compilation and flashing, Project creation steps.</li> <li>➤ Variables, Data Types and Registers: Embedded data types, Use of volatile keyword, Register mapping and addressing.</li> <li>➤ Control Structures and Functions: Loops (for, while), Conditional statements, Functions and modular programming.</li> <li>➤ Interrupt Programming in C: Writing ISR, Enabling and disabling interrupts, Practical examples.</li> <li>➤ Peripheral Programming: GPIO (LED, switch), Timer (delay, PWM), ADC (sensor reading), DAC basics.</li> <li>➤ Communication Protocols: UART, SPI, I2C, Basic program examples.</li> <li>➤ Debugging Techniques: Software debugging (breakpoints, watch variables), Hardware debugging, Common errors and troubleshooting.</li> </ul>		
3.	<p><b>Applications of Digital Signal Controllers</b> Contents:</p> <ul style="list-style-type: none"> <li>➤ DSC in Power Electronics: DC-DC converters (Buck, Boost), Inverters (Single-phase, Three-phase).</li> <li>➤ Motor Control Applications: Speed control of DC motor, Basics of induction motor control.</li> <li>➤ Renewable Energy Applications: Solar MPPT control, Grid-connected inverter systems.</li> <li>➤ Control Techniques: Open-loop control, Closed-loop control, Introduction to PID controller.</li> <li>➤ Real-Time Implementation Challenges: Sampling time, Switching frequency, Noise and filtering issues.</li> </ul>	08	18 %
4.	<p><b>STM32 and TI Controller Practical Concepts</b> Contents:</p> <ul style="list-style-type: none"> <li>➤ Introduction to STM32 Controllers: Features and pin configuration, GPIO configuration.</li> <li>➤ STM32 Programming Basics: Digital I/O, Timer-based delay, PWM generation.</li> </ul>	10	22 %



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	<ul style="list-style-type: none"> <li>➤ STM32 in Power Electronics: PWM for converters (Buck, Boost, Inverter), ADC for voltage/current sensing.</li> <li>➤ Introduction to TI Controllers: TI C2000 series overview, Comparison with STM32, Advantages in real-time control.</li> <li>➤ Basic TI Controller Concepts: High-speed PWM modules, ADC synchronization, Control loop basics.</li> </ul>		
5.	<p><b>Introduction to PLL and FPGA</b> Contents:</p> <ul style="list-style-type: none"> <li>➤ Phase Locked Loop (PLL): Basic concept, Block diagram (Phase detector, Loop filter, VCO), Applications (Frequency and grid synchronization).</li> <li>➤ Introduction to FPGA: Concept of FPGA, Difference between Microcontroller and FPGA, Architecture (Logic blocks, interconnections, I/O).</li> <li>➤ FPGA vs DSC: Speed comparison, Parallel vs sequential processing, Advantages and limitations.</li> <li>➤ Basic FPGA Applications: PWM generation, Signal processing, High-speed control systems.</li> </ul>	5	11 %
	<b>Total</b>	<b>45</b>	<b>100</b>

**Suggested Specification Table with Marks (Theory):**

<b>Distribution of Theory Marks (in %)</b>					
<b>R Level</b>	<b>U Level</b>	<b>A Level</b>	<b>N Level</b>	<b>E Level</b>	<b>C Level</b>
25 %	35 %	40 %	-	-	-

*Where R: Remember; U: Understanding; A: Application, N: Analyze and E: Evaluate C: Create (as per Revised Bloom's Taxonomy)*

**References/Suggested Learning Resources:**

**(a) Books:**

1. **Embedded Systems with ARM Cortex-M Microcontrollers and Assembly Language Programming** – Muhammad Ali Mazidi, Sarmad Naimi, Sepehr Naimi, Edition: First Edition (2017), ISBN: 978-0997925944, Publisher: MicroDigitalEd



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2. **Embedded Systems: Real-Time Interfacing to ARM Cortex-M Microcontrollers** – Jonathan W. Valvano, Edition: Third Edition (2014), ISBN: 978-1463590154, Publisher: CreateSpace
3. **Microprocessor Architecture, Programming and Applications with 8085** – Ramesh S. Gaonkar, Edition: Sixth Edition (2013), ISBN: 978-8131705858, Publisher: McGraw Hill Education
4. **Digital Signal Processing: Principles, Algorithms and Applications** – John G. Proakis, Dimitris G. Manolakis, Edition: Fourth Edition (2006), ISBN: 978-0131873742, Publisher: Pearson
5. **The Definitive Guide to ARM Cortex-M3 and Cortex-M4 Processors** – Joseph Yiu, Edition: Third Edition (2013), ISBN: 978-0124080829, Publisher: Elsevier
6. **Modern Power Electronics and AC Drives** – Bimal K. Bose, Edition: First Edition (2002), ISBN: 978-0130167439, Publisher: Prentice Hall
7. **Fundamentals of Analog and Digital Electronic Circuits** – Bahaa E. A. Saleh, Malvin C. Teich, Edition: Second Edition (2009), ISBN: 978-0471714484, Publisher: Wiley

## (b) Open-source software and website:

1. **Texas Instruments – C2000 Series Documentation and Development Tools** – Publisher: Texas Instruments, Available at: <https://www.ti.com>
2. **NPTEL – Courses on Embedded Systems, Power Electronics and Control Systems** – Organization: NPTEL, Available at: <https://nptel.ac.in>
3. **STM32CubeIDE – Integrated Development Environment for STM32 Programming** – Software by STMicroelectronics
4. **Code Composer Studio – Development Tool for TI Controllers** – Software by Texas Instruments
5. **MATLAB / Simulink – Simulation of Control Systems and Power Electronics** – Software by MathWorks
6. **Xilinx Vivado – FPGA Design and Implementation Tool** – Software by Xilinx

## Suggested Course Practical List:

Sr. No.	Practical Outcome/Title of Experiment	CO1	CO2	CO3	CO4	CO5
1	To study and understand the architecture, features, and development environment of STM32 / TI C2000 controller.	√				
2	To implement LED blinking using GPIO interfacing on STM32 / TI C2000 controller.		√			



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3	To interface a push button, switch with LED and control its operation using GPIO on STM32 / TI C2000 controller.		√			
4	To generate accurate time delay using timer module of STM32 / TI controller		√			
5	To implement external interrupt using push button input and observe interrupt handling using STM32 / TI C2000 controller.		√			
6	To implement timer-based interrupt for periodic event control		√			
7	To generate PWM signal using timer and vary duty cycle for control applications STM32 / TI C2000 controller.			√	√	
8	To interface Analog to Digital Converter (ADC) for reading analog input signal using STM32 / TI C2000 controller.			√		
9	To generate analog output using Digital to Analog Converter (DAC) using STM32 / TI C2000 controller.			√		
10	To interface sensors (temperature/voltage/current) using ADC and analyze readings using STM32 / TI C2000 controller.			√		
11	To implement UART communication for serial data transmission and reception.			√		
12	To implement SPI communication protocol for high-speed data transfer.			√		
13	To implement I2C communication protocol for multi-device interfacing.			√		
14	To control speed of DC motor using PWM technique any micro controller.				√	
15	To implement PWM control for DC-DC Buck converter and observe output voltage variation using STM32 / TI C2000 controller.				√	
16	To implement PWM control for DC-DC Boost converter and analyze voltage gain characteristics using STM32 / TI C2000 controller.				√	
17	To implement single-phase inverter using PWM technique and observe output waveform using STM32 / TI C2000 controller.				√	



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18	To implement closed-loop control system using basic PID controller and analyze performance using STM32 / TI C2000 controller.					√
19	To study and simulate Phase Locked Loop (PLL) operation and its applications					√
20	To implement PWM generation using FPGA through simulation or hardware demonstration.					√

## List of Laboratory/Learning Resources Required:

Sr. No.	Equipment Name with Broad Specifications
1	<b>STM32 Development Board</b> – 32-bit ARM Cortex-M (STM32F4), up to 168 MHz, Flash: 512 KB–1 MB, SRAM: 128–256 KB, Peripherals: GPIO, ADC, DAC, UART, SPI, I2C, USB and debugging support.
2	<b>TI C2000 Development Board</b> – 32-bit DSP controller (TMS320F28379D), High-speed PWM, fast ADC, real-time control capability, communication interfaces: SPI, I2C, UART.
3	<b>FPGA Development Board (Intel Cyclone V)</b> – Up to ~110K logic elements with DSP blocks, DDR3 support, high-speed processing, interfaces: GPIO, UART, SPI, I2C, USB (JTAG), supports VHDL/Verilog.
4	<b>Digital Storage Oscilloscope (DSO)</b> – Bandwidth: 50–100 MHz, $\geq 2$ channels, $\geq 1$ GS/s sampling rate, used for waveform and PWM signal analysis.
5	<b>Communication Interface Modules</b> – UART-to-USB, SPI and I2C modules, external sensors and EEPROM.
6	<b>Power Electronics Trainer Kit</b> – Buck, Boost and H-bridge inverter modules, PWM control with protection circuits.
7	<b>Regulated DC Power Supply</b> – Output: 0–30V adjustable, current: 2–5 A, overload and short-circuit protection.
8	<b>Function Generator</b> – Frequency range: 1 Hz – 1 MHz, outputs: sine, square and triangle waves, adjustable amplitude and duty cycle.



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## Suggested Project List:

1. Implement closed-loop control (basic PID simulation or hardware).
2. Demonstrate ADC-based voltage/current sensing system.
3. Study and simulate PLL operation (software or MATLAB/Simulink).
4. Study basic FPGA implementation for PWM generation (simulation/demo).
5. Mini Project: Develop a real-time embedded system (e.g., motor control / converter control).

## Suggested Activities for Students:

Other than the classroom and laboratory learning, following are the suggested student-related *co-curricular* activities which can be undertaken to accelerate the attainment of the various outcomes in this course. Students should perform following activities in group (or individual) and prepare reports of about 5 pages for each activity. They should also collect/record physical evidence for their (student's) portfolio which may be useful for their placement interviews:

1. Perform **hands-on programming** using STM32 / TI controllers for real-time applications.
2. Develop **mini projects** related to power electronics (converter/inverter control) and motor control.
3. Conduct **simulation studies** of DC-DC converters, inverters, and control techniques using tools like MATLAB/Simulink.
4. Practice **embedded C programming** for peripheral interfacing (GPIO, ADC, PWM, UART, SPI, I2C).
5. Participate in **technical workshops / webinars** on embedded systems, FPGA, and real-time control.
6. Analyze **case studies** on renewable energy systems such as solar MPPT and grid-connected inverters.
7. Implement **closed-loop control systems** (basic PID controller) in simulation or hardware.
8. Explore **debugging techniques** using IDE tools (breakpoints, watch variables, debugging hardware).
9. Work on **team-based projects** to develop problem-solving and collaborative skills.
10. Prepare and present **technical seminars** on advanced topics like PLL, FPGA, and DSC applications.
11. Engage in **self-learning** through online platforms, datasheets, and reference manuals of STM32 and TI controllers.

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